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# EtherCAT

× EtherCAT Master 가

## Initial AIState

- IDE , AIState
  - Initial : 'Initial'
  - Pre-OP : 'Pre-OP'
  - Safe-OP : 'Safe-OP'
  - OP : 'OP'
  - Don't Change :

×

- Setup <sup>1)</sup>, 'OP' ' **EEPROM Read Failed**'

## IO

- MotionIO Visible : , Driver MotionIO((EL, ORG )  
IO
- Using LocalCh : LocalCh Master , Local

## Software Emergency

- StopMode : Software Emergency 가 ,
  - Emergency Stop :

1)

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