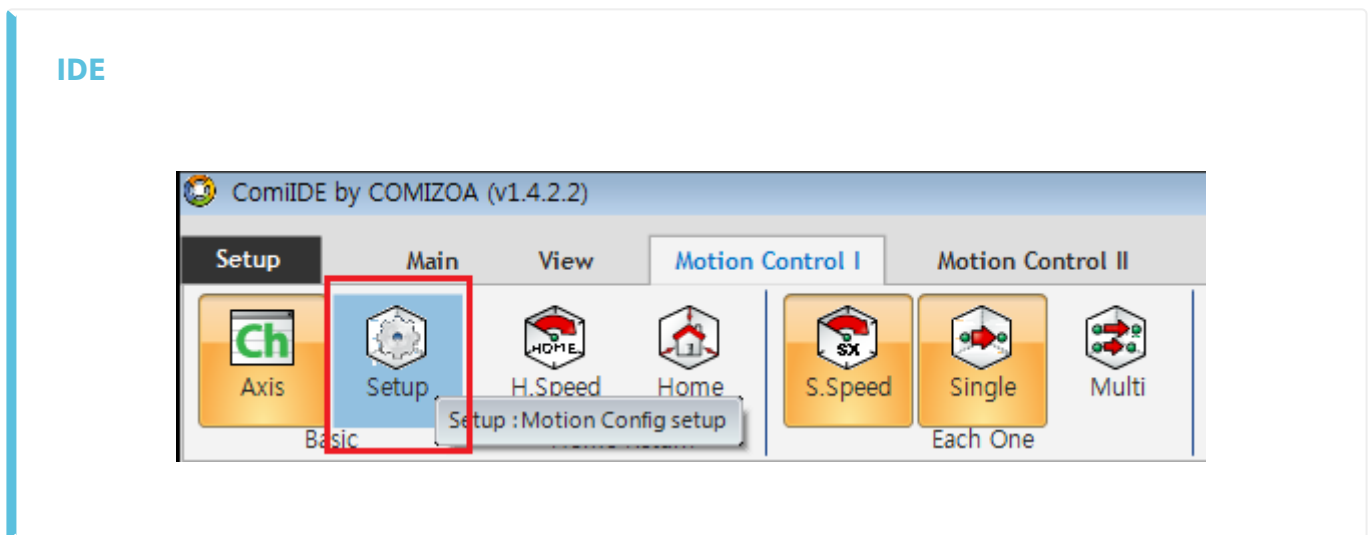
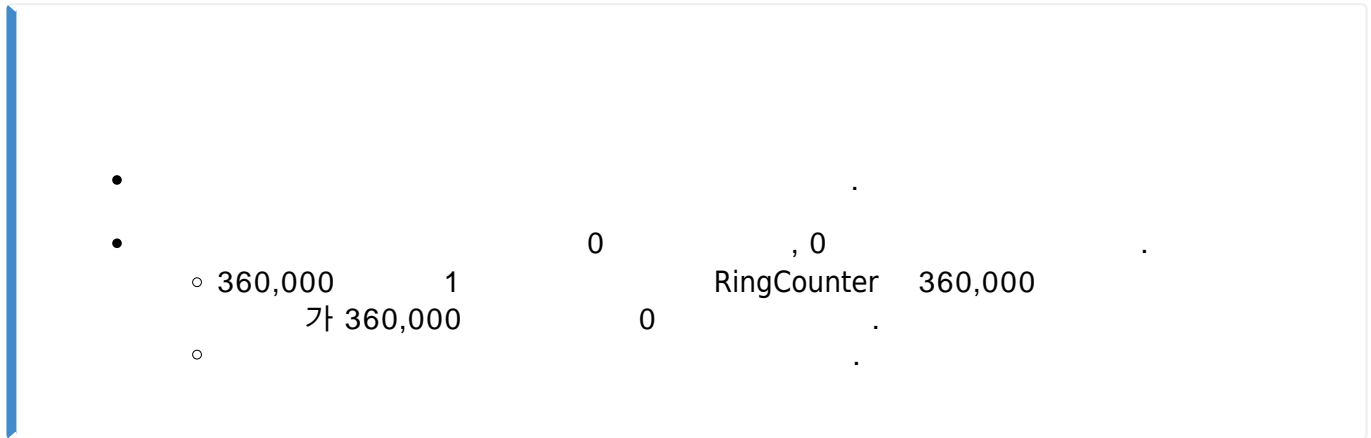


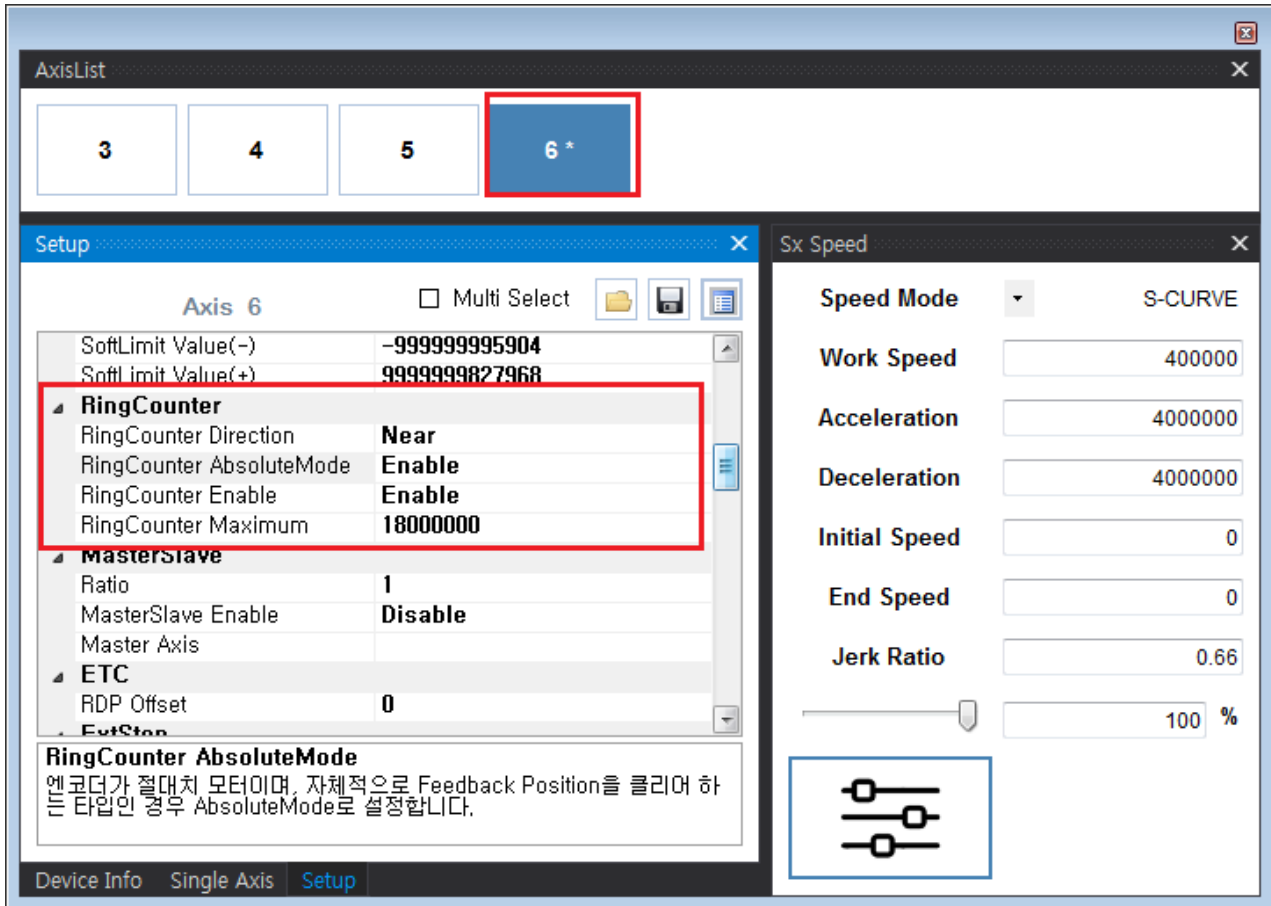
IDE 1
..... 1

Ring Counter

x (Ring Counter)



- **Motion Control I Setup**



RingCounter

'RingCounter Enable'

'Enable'

- RingCounter Direction :
 - Negative : (-)
 - Positive : (+)
 - Near : 가
 - Far :
- RingCounter AbsoluteMode : Motor Type
 - Enable : Motor Type Absoulte
 - Disable : Motor Type Incremental
- RingCounter Enable
 - Enable : RingCounter
 - Disable : RingCounter
 - Absolute Type , Position Maximum
 - Maximum
- RingCounter Maximum : RingCounter Range
 - 0 ~ Maximum - 1
 - Maximum 10,000 0 ~ 9999
 - UnitDistance , 0 ~ (Maximum - 1) / UnitDistance
 - Maximum 10,000 , UnitDistance가 200 , 0 ~ 49.995

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