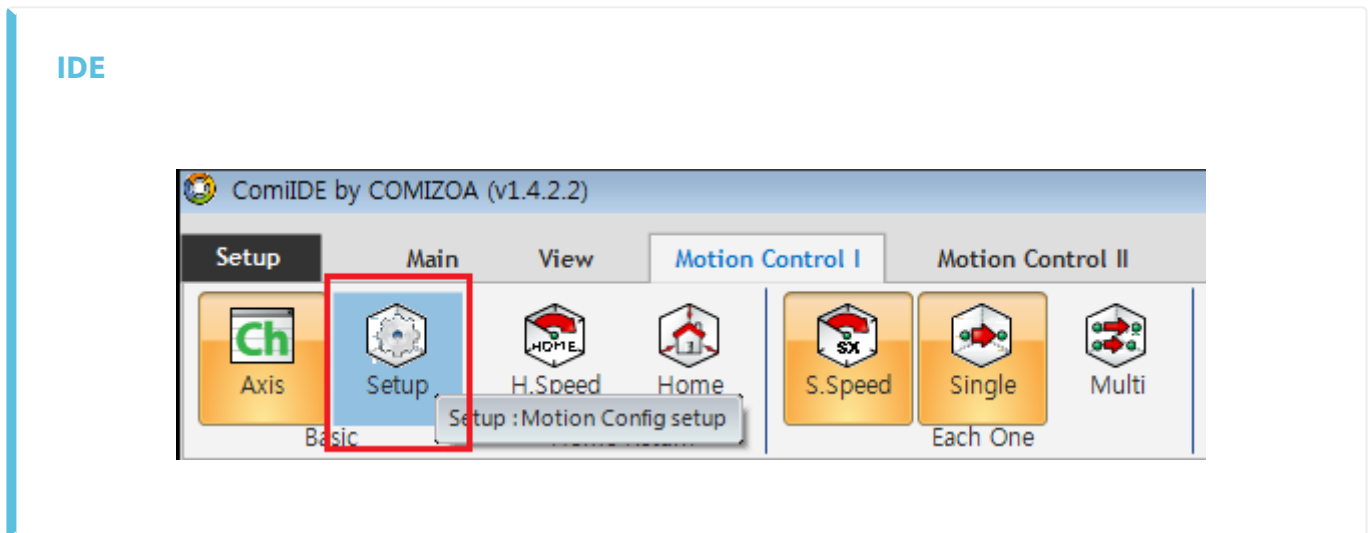
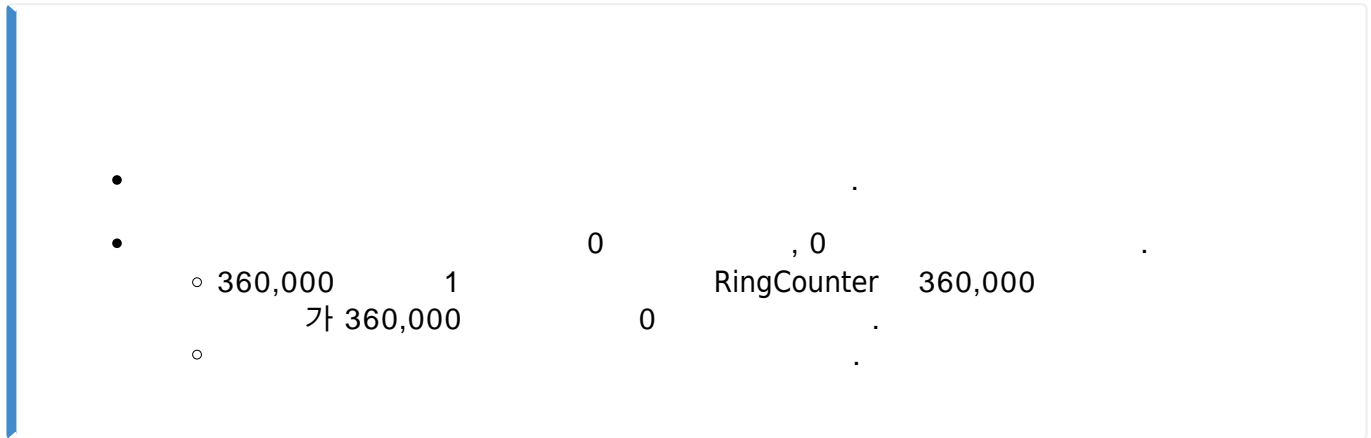


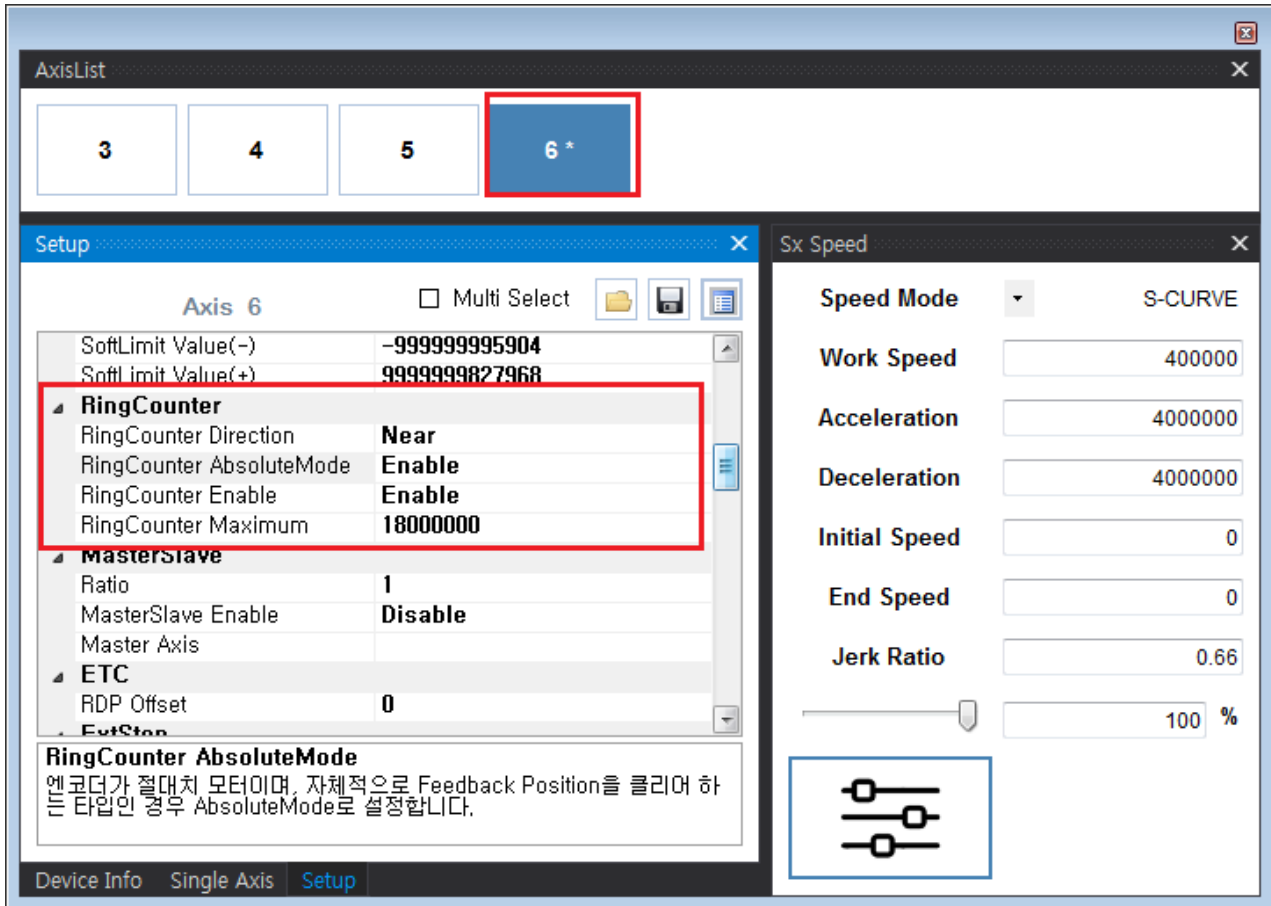
IDE	.....	1
	.....	1

# Ring Counter

x (Ring Counter)



- Motion Control I Setup



**RingCounter**

**'RingCounter Enable'**

**'Enable'**

- RingCounter Direction :
  - Negative : (-)
  - Positive : (+)
  - Near : 가
  - Far :
- RingCounter AbsoluteMode : Motor Type
  - Enable : Motor Type Absoulte
  - Disable : Motor Type Incremental
- RingCounter Enable
  - Enable : RingCounter
  - Disable : RingCounter
    - Absolute Type , Position Maximum
    - Maximum
- RingCounter Maximum : RingCounter Range
  - 0 ~ Maximum - 1
    - Maximum 10,000 0 ~ 9999
  - UnitDistance , 0 ~ (Maximum - 1) / UnitDistance
    - Maximum 10,000 , UnitDistance가 200 , 0 ~ 49.995

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Last update: **2024/07/08 18:23**