

WriteOne 1
Write 1:N 2
Write N:N 2
EepOne / EepAll 2

(Write)

x

WriteOne

• 'Axis 4'

Item	Name	Minimum	Maximum	Defalut	Servo	Value	Unit
42	Max position limit	-2147483648	2147483647	0	0	0	1 unit
<input checked="" type="checkbox"/>	Polarity	0	255	0	0	224	---
44	Max profile velocity	0	4294967295	104857600	104857600	104857600	1 unit/s
45	Max motor speed	0	4294967295	6000	5000	5000	1 r/min

• **Bold**

10 16

Write One Cancel

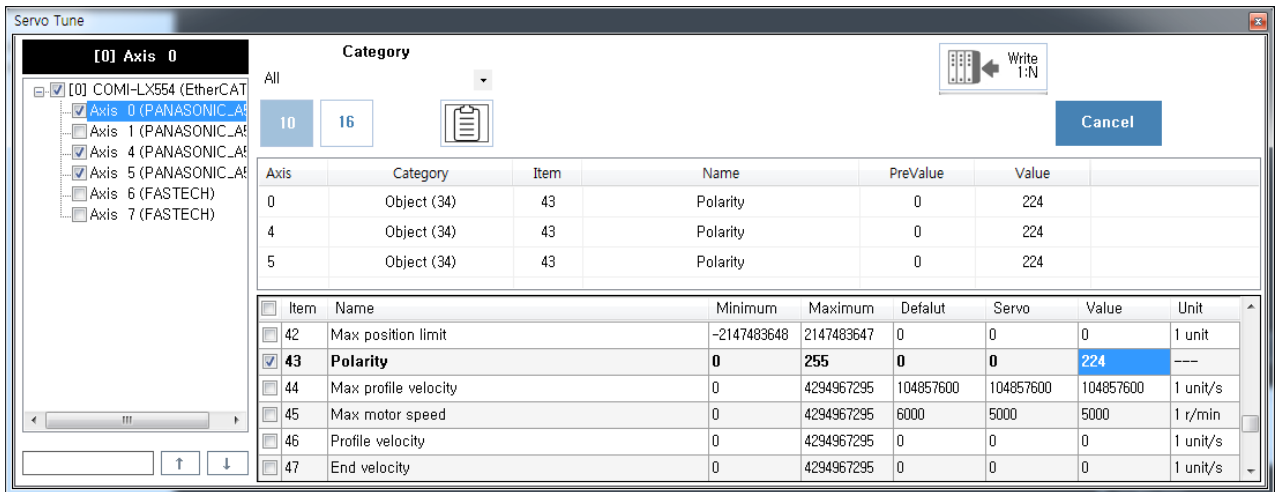
Axis	Category	Item	Name	PreValue	Value
0	Object (34)	43	Polarity	0	224

Item	Name	Minimum	Maximum	Defalut	Servo	Value	Unit
42	Max position limit	-2147483648	2147483647	0	0	0	1 unit
<input checked="" type="checkbox"/>	Polarity	0	255	0	0	224	---
44	Max profile velocity	0	4294967295	104857600	104857600	104857600	1 unit/s
45	Max motor speed	0	4294967295	6000	5000	5000	1 r/min
46	Profile velocity	0	4294967295	0	0	0	1 unit/s

- WriteOne
- WriteOne

Write 1:N

AxisList



- Polarity 'Axis 0', 'Axis 4', 'Axis 5'
- AxisList (Vendor)
- AxisList

Write N:N

- AxisList

EepOne / EepAll

- 가 EEPROM (store) ¹⁾
- (store) ²⁾
- EEPROM ³⁾

comizoa, , ide, ethercat, , servotunes, , write, , eeprom

1) , 3)

2)

, MainIndex : 0x1010, SubIndex : 1, size : 4, val : 0x65766173,

CompleteAccess : 0

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