

WriteOne ..... 1  
Write 1:N ..... 2  
Write N:N ..... 2  
EepOne / EepAll ..... 2

# (Write)

x

**WriteOne**

• 'Axis 4'

Item	Name	Minimum	Maximum	Defalut	Servo	Value	Unit
<input type="checkbox"/>	42 Max position limit	-2147483648	2147483647	0	0	0	1 unit
<input checked="" type="checkbox"/>	<b>43 Polarity</b>	<b>0</b>	<b>255</b>	<b>0</b>	<b>0</b>	<b>224</b>	---
<input type="checkbox"/>	44 Max profile velocity	0	4294967295	104857600	104857600	104857600	1 unit/s
<input type="checkbox"/>	45 Max motor speed	0	4294967295	6000	5000	5000	1 r/min

• **Bold**

10 16

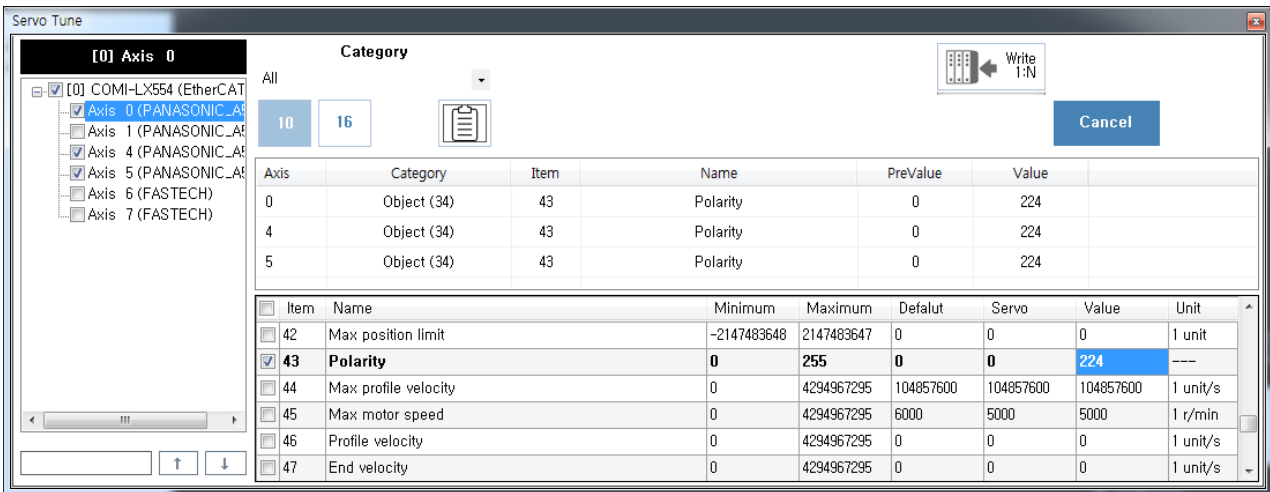
Axis	Category	Item	Name	PreValue	Value
0	Object (34)	43	Polarity	0	224

Item	Name	Minimum	Maximum	Defalut	Servo	Value	Unit
<input type="checkbox"/>	42 Max position limit	-2147483648	2147483647	0	0	0	1 unit
<input checked="" type="checkbox"/>	<b>43 Polarity</b>	<b>0</b>	<b>255</b>	<b>0</b>	<b>0</b>	<b>224</b>	---
<input type="checkbox"/>	44 Max profile velocity	0	4294967295	104857600	104857600	104857600	1 unit/s
<input type="checkbox"/>	45 Max motor speed	0	4294967295	6000	5000	5000	1 r/min
<input type="checkbox"/>	46 Profile velocity	0	4294967295	0	0	0	1 unit/s

- WriteOne
- WriteOne

### Write 1:N

#### AxisList



- Polarity 'Axis 0', 'Axis 4', 'Axis 5'
- AxisList (Vendor)
- AxisList

### Write N:N

- AxisList

### EepOne / EepAll

- 가 EEPROM (store) <sup>1)</sup>
- (store) <sup>2)</sup>
- EEPROM <sup>3)</sup>

comizoa, , ide, ethercat, , servotunes, , write, , eeprom

1) 3)

2)

, MainIndex : 0x1010, SubIndex : 1, size : 4, val : 0x65766173,

CompleteAccess : 0

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Last update: **2024/07/08 18:23**