

Case 1 ..... 1  
    AddInfo ..... 1  
    Cause ..... 1  
    Solution ..... 1  
Case 2 ..... 1  
    AddInfo ..... 1  
    Cause\_Solution ..... 1

× 가 .

### Case 1

**AddInfo**

- Command Position

**Cause**

- Alarm Limit ON
- Software Limit

**Solution**

- Alarm Limit
- Software Limit

### Case 2

**AddInfo**

- Command position 가

**Cause\_Solution**

- Motion Controller 24V . 24V

- Open-collector (or ) 가 Line-drive
- SERVO-ON . SERVO-OFF
- Alarm Clear Alarm Clear 가 Active
- Alarm Clear 가 Active
- 가
- 가
- 가

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