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Process Data Setup 1

Touch Probe Setup

× 터치프로브 사용을 위한 설정 안내 페이지입니다.

Process Data Setup

- 터치프로브를 사용하기 위해서는 해당 오브젝트가 PDO에 반드시 포함되어야 합니다.
 - PDO에 포함시키는 방법은 **Process Data 변경** 을 참조하시기 바랍니다.
- InPDO 설정
- SyncManager - Outputs 선택
- PDO Assignment 탭에서 PDO Contents에 해당 오브젝트(0x60B8등)가 포함된 PDO Map 선택 (체크)

Configurator

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Topology Net Info Slave Info **ProcessData**

#00 [02FFh] MASTER-DC
#01 [0011h] MADHT1505BA1
#02 [0012h] MADHT1505BA1

SyncManager

SM	Size	Type
<input checked="" type="checkbox"/>	0	256 MBoxOut
<input checked="" type="checkbox"/>	1	256 MBoxIn
<input checked="" type="checkbox"/>	2	19 Outputs
<input checked="" type="checkbox"/>	3	25 Inputs

PDO List

Index	Size	Name	SM
0x1600	9	Receive PDO mapping 1	
0x1601	19	Receive PDO mapping 2	2
0x1602	15	Receive PDO mapping 3	
0x1603	21	Receive PDO mapping 4	
0x1A00	23	Transmit PDO mapping 1	
0x1A01	25	Transmit PDO mapping 2	3
0x1A02	25	Transmit PDO mapping 3	
0x1A03	25	Transmit PDO mapping 4	

PDO Assignment

Index	Addr
<input type="checkbox"/>	0x1600
<input checked="" type="checkbox"/>	0x1601
<input type="checkbox"/>	0x1602
<input type="checkbox"/>	0x1603

PDO Contents (0x1601)

Index	Size	Name	Type
0x6040:00	2	Controlword	UINT
0x6060:00	1	Modes of operation	SINT
0x6071:00	2	Target torque	INT
0x607A:00	4	Target position	DINT
0x6080:00	4	Max motor speed	UDINT
0x60B8:00	2	Touch probe function	UINT
0x60FF:00	4	Target velocity	DINT

Apply AutoAddress To Servo Apply to the same product.

- OutPDO 설정
- SyncManager - Inputs 선택
- PDO Assignment 탭에서 PDO Contents에 해당 오브젝트(0x60B9등)가 포함된 PDO Map 선택 (체크)

Configurator

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#00 [02FFh] MASTER-DC
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SM	Size	Type
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0x1A01	25	Transmit PDO mapping 2	3
0x1A02	25	Transmit PDO mapping 3	
0x1A03	25	Transmit PDO mapping 4	

PDO Assignment

Index	Type
<input type="checkbox"/> 0x1A00	
<input checked="" type="checkbox"/> 0x1A01	
<input type="checkbox"/> 0x1A02	
<input type="checkbox"/> 0x1A03	

PDO Contents (0x1A01)

Index	Size	Name	Type
0x603F:00	2	Error code	UINT
0x6041:00	2	Statusword	UINT
0x6061:00	1	Modes of operation display	SINT
0x6064:00	4	Position actual value	DINT
0x606C:00	4	Velocity actual value	DINT
0x6077:00	2	Torque actual value	INT
0x60B9:00	2	Touch probe status	UINT
0x60BA:00	4	Touch probe pos1 pos value	DINT

Index Addr

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