
Case 1	1
AddInfo	1
Cause	1
Solution	1
Config Info	2
Case 2	2
AddInfo	2
Cause	2
Solution	3
Case 3	3
AddInfo	3
Cause	3
Solution	3
Case 4	3
AddInfo	3
Cause	3
Solution	4

, , torque, , ,

x 가 .

Case 1

AddInfo

(Cyclic Torque Mode)

Target Torque

가

가

.

Cause

- OutPDO Data Torque

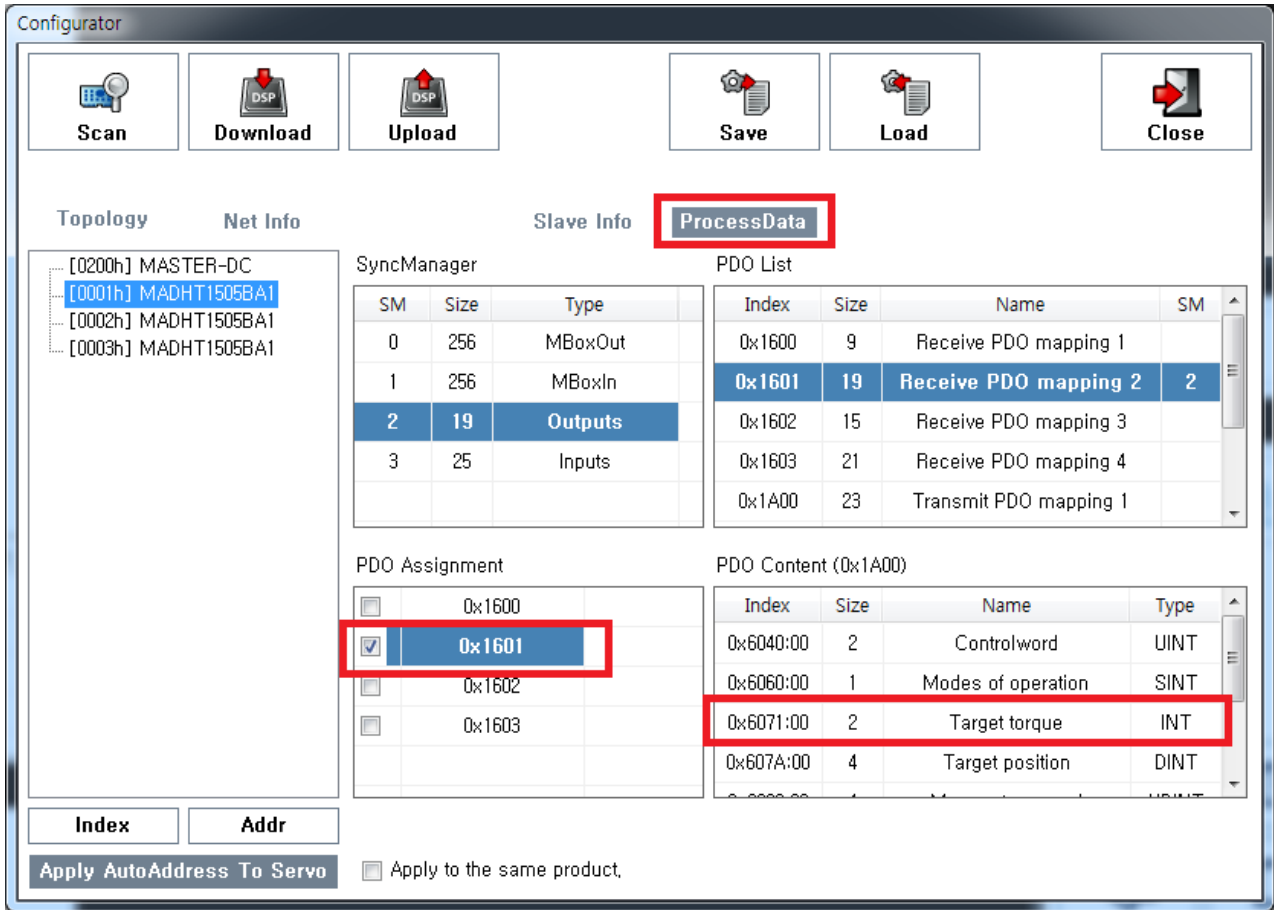
-

1)

Solution

- OutPDO Data Torque
 - Torque

가 Configuration
OutPDO Map



- Config

Configuration Guide

- XML

. (OMRON xml)

- Torque Monitor가

Torque Monitor Failed

×
Config Info



Case 2

AddInfo

-

Cause

- SDO 0x6080 (Max motor speed) 0 2)

Solution

- SDO 0x6080 (Max motor speed)
- rpm

Case 3

AddInfo

-

Cause

- Pr0.00 0
-
- (Polarity)³⁾ , 0x607E

Solution

- Pr0.00 0

Case 4

AddInfo

-

Cause

- Pr0.08 0
- **PANASONIC :**

Solution

- Pr0.08 0

1)

OutPDO Data

2)

Omron 0x607F (Max Profile Speed)

3)

No Reverse : 0 / Reverse : 224

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