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EtherCAT

# Introduce

## Equipment : Clean

### Summary

- 

### Part

- Master
- PC
- IO Module

### UI

- MFC
- Transfer Robot :

### History

#### 18.10.16

- ( , )
  - Class Portion
  - Class Single Axis

#### 18.10.17

- ( , )
  - COMIZOA Class , State Monitor
  - SMI Class

#### 18.10.18

- COMIZOA Class 가 : HomeReturn ( )
- 

#### 18.10.19

- ( , )
  - ,
  -

#### 18.10.30

- , (?) ( )

- NozzleControl(ListMotion), robot\_peak & robot\_place (CMP Callback)
- 4

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